

Manufactured with  
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## S33BL-CAN

Engineered and Manufactured in South Korea

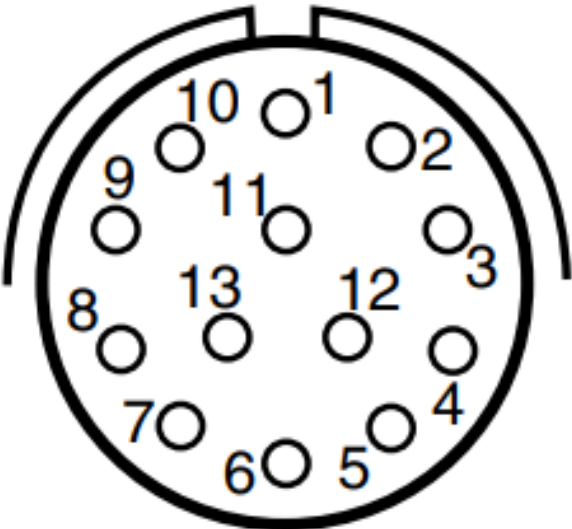
## 1 Performance Specification

Model	SR33BL-CAN-T-24V	-
Control System	CAN2.0A,B	
Position Type	Contactless Magnetic Encoder	
Motor Type	BLDC Motor	
Operating Voltage Range	-	18.0V ~ 32.0V
Voltage	-	At 24.0V
No Load Speed	200 °/sec	
	0.3 sec/60°	
	33 RPM	
Rated Torque (At 20% Load)	7.84 N·m (80.0 kgf·cm)	
Peak Torque	39.24 N·m (400.0 kgf·cm)	
Idle Current (At Stopped)		30mA
Running Current (At No Load)		1,000mA
Peak Current		2,100mA
Operating Travel	Servo Mode : ±60°( Default), ±150°( Programmable)	
Multi-Turn	Turn Mode : ±32760 turns	
Continuous Mode	N/A	
Temperature Sensing	Enabled (MCU, Motor)	
Voltage Sensing	Enabled	
Current Sensing	Enabled	
Humidity Sensing	Enabled	
Servo Amplifier Type	32bit Programmable Digital	

## 2 Mechanical Features

Connector Type		Dual Circular
Dimensions	100.0 x 33.0 x 195.0 mm (±0.2mm) / (3.937 x 1.299 x 7.677 inch)	
Weight		1400.0g (49.24oz)
Housing	Rugged Aluminum Alloy With Hardcoat Anodizing (MIL-A-8625 Type III)	
Gear Reduction	5 Hardened Steel Gears	
Bearing	2 Ball Bearing & 6 Needle Bearing 1 Thrust Bearing	
Horn Gear Spline	Square 10 x 10mm (0.394 inch)	
Gear Train Backlash	< 0.5°	
Slip Clutch Release Momentum	N/A	
Radial Load On Output Shaft	< 3,924N (400kgf)	
Push Load On Output Shaft	< 5,886N (600kgf)	

### 3 Connector

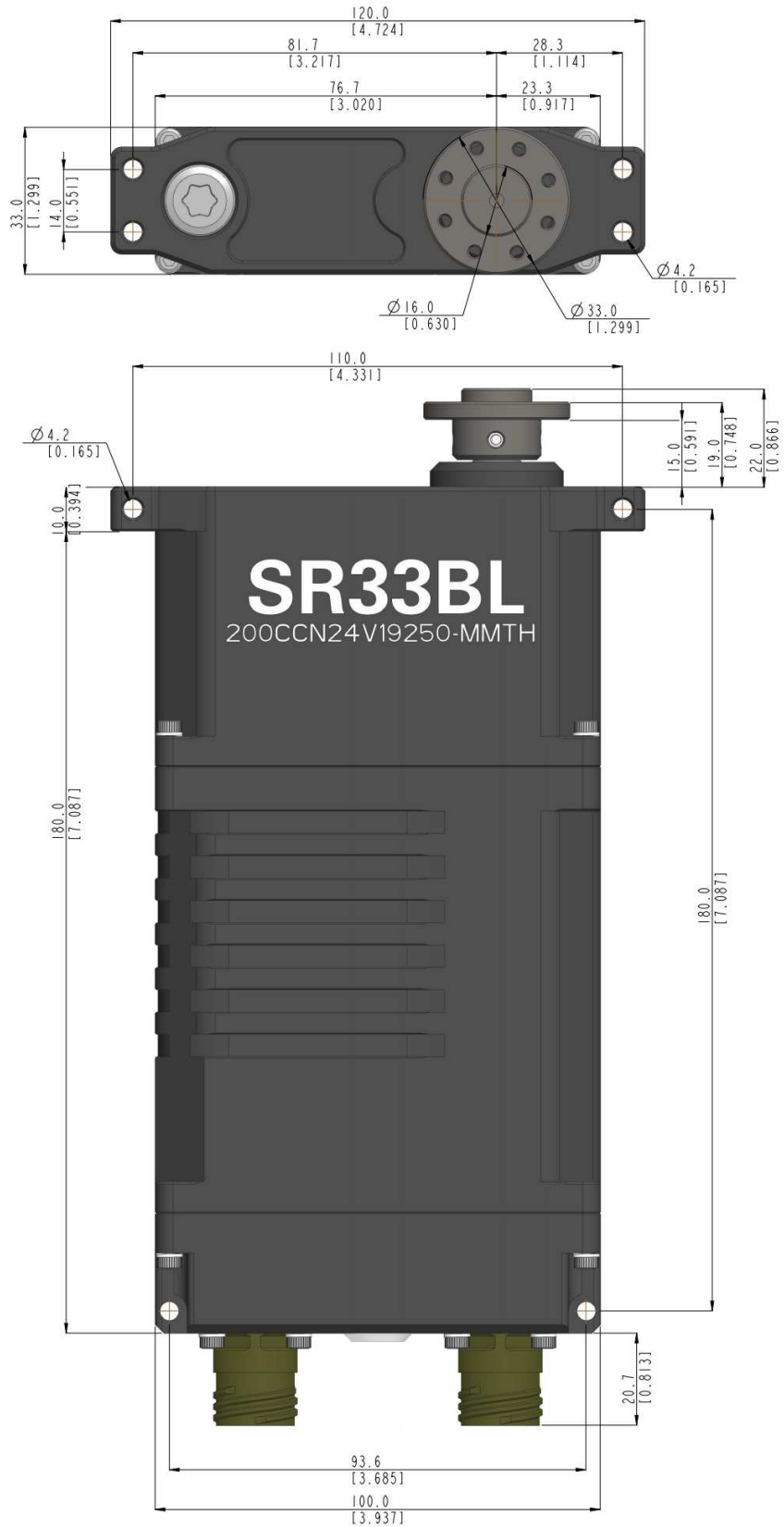
<b>Manufacture</b>	AMPHENOL		
<b>Type</b>	AMPHENOL_D38999-20WB35PN.		
<b>Mating</b>	AMPHENOL_D38999/26WB35SN		
<b>Pin Assignment</b>	Circular Type Connector		
		<b>1</b>	NC
		<b>2</b>	VCC
		<b>3</b>	NC
		<b>4</b>	CAN-High
		<b>5</b>	CAN-Low
		<b>6</b>	CASE_GND
		<b>7</b>	NC
		<b>8</b>	NC
		<b>9</b>	NC
		<b>10</b>	VCC
		<b>11</b>	NC
		<b>12</b>	GND
		<b>13</b>	GND

## 4 Environmental Specifications

<b>Operation Temperature</b>	-40°C (-40°F)	MIL-STD-810G Method 502.5
	+80°C (+176°F)	MIL-STD-810G Method 501.5
<b>Storage Temperature</b>	-40°C (-40°F)	MIL-STD-810G Method 502.5
	+80°C (+176°F)	MIL-STD-810G Method 501.5
<b>Humidity</b>	95% @35°C ~ 60°C @300hours	MIL-STD-810G Method 507.5
<b>IP-Rating</b>	IP68	IEC 60529
<b>Vibration</b>	Orthogonal axes : $\pm X$ , $\pm Y$ , $\pm Z$ from 50 ~ 500Hz Duration : sweep 5min Acceleration 30G Displacement : 5mm	MIL-STD-810G 514.6C-VII EN 60068-2-6
<b>Mechanical Shock</b>	Procedure 1 - Functional shock 20g, 11ms, Sawtooth Waveform	MIL-STD-810G 516.6
<b>EMC</b>	EN 61000-4-2 EN 61000-4-3 EN 55016-2-1 EN 55016-2-3	EN 61000-6-2:2005+Cor.:2005 EN 61000-6-3:2007+A1:2011
<b>MTTF</b>	>1,000h	Test Condition Load : 20% of Max Torque 0.5Hz Extream(-60° < > 0 < > +60°)

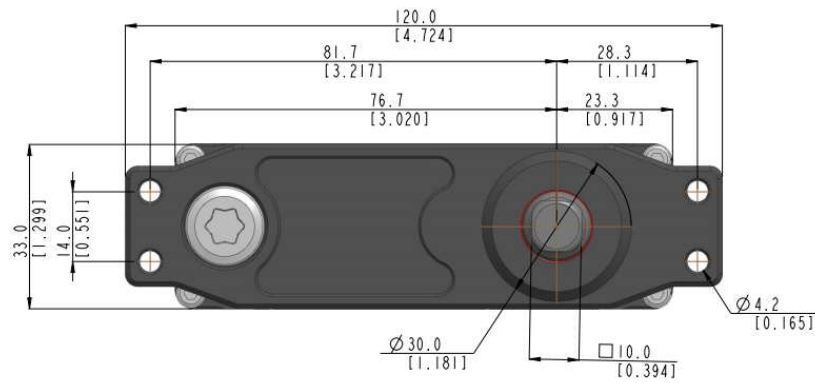
## Dimensions

### 5-1 CIRCULAR CONNECTOR TYPE – WITH HORN



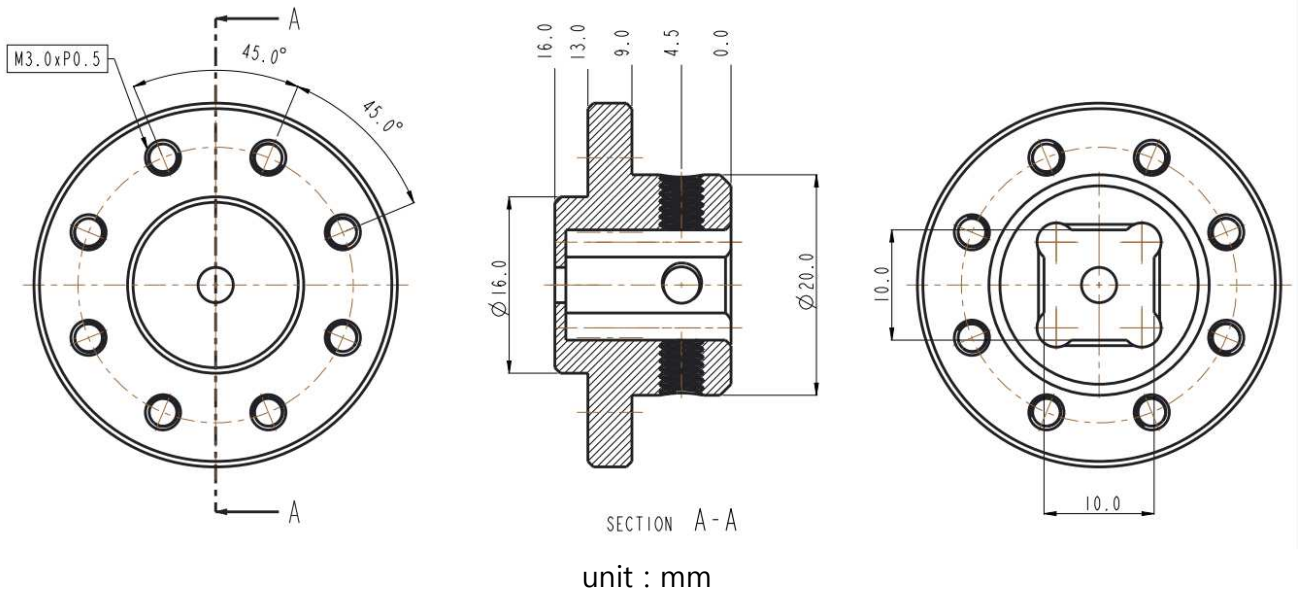
unit : mm [inch]

## 5-2 CIRCULAR CONNECTOR TYPE – WITHOUT HORN

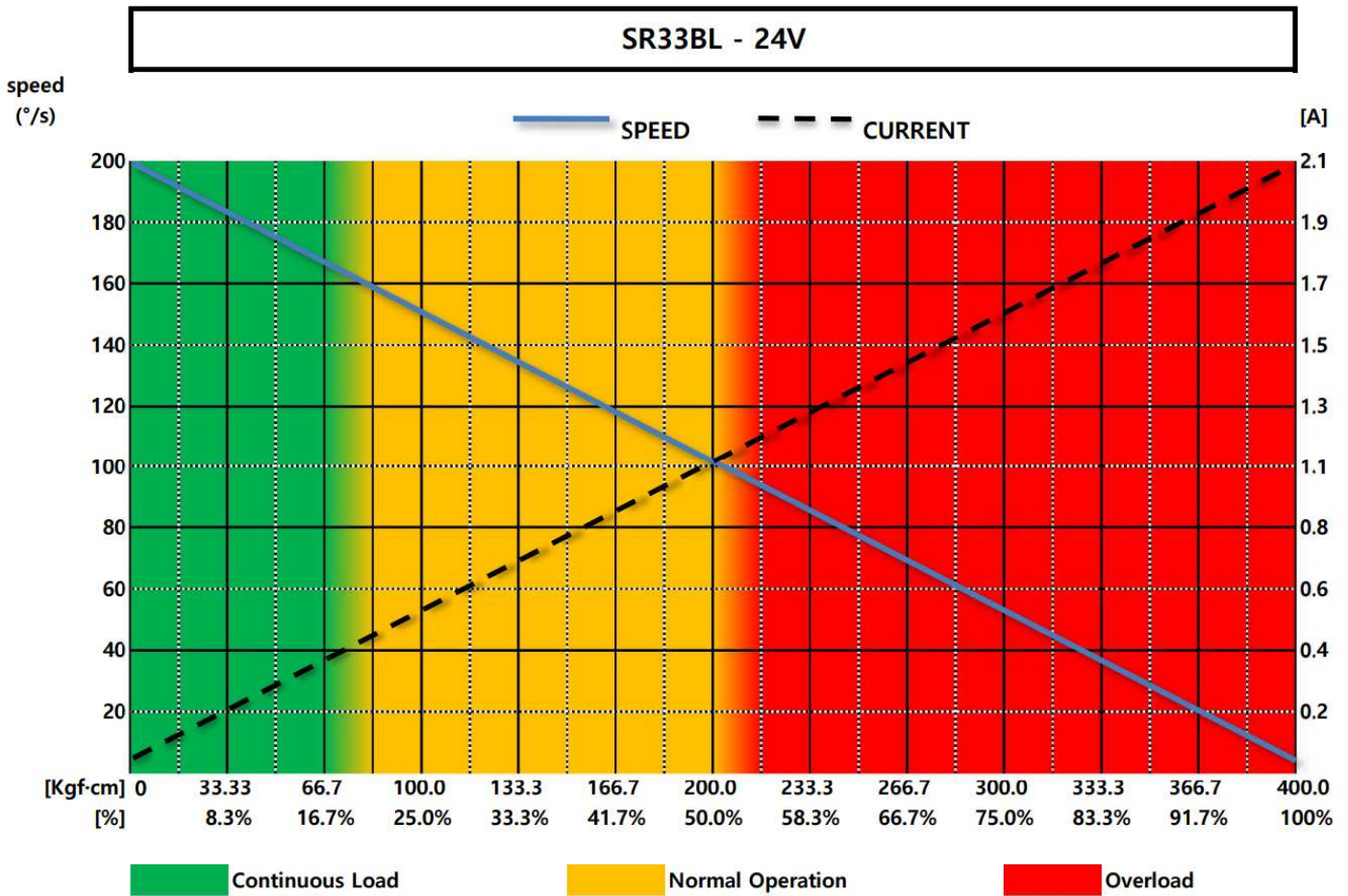


unit : mm [inch]

### 5 Dimensions – Accessory



### 6 Performance Graph



## 7 Changes

Data	Version	Updates

## REFERENCES

- ✓ For the protocol manuals of CAN, DroneCAN, RS485 and TTL, please contact Hitec RCD Korea.  
( [industrial.sales@hitecrd.net](mailto:industrial.sales@hitecrd.net) )
- ✓ If you would like to purchase additional industrial servos, please contact Hitec Network or local Hitec distributors in your place.  
( <https://hitecrd.com/contact-us/international-distributors> )
- ✓ This product should not be used directly on the human body for medical purposes.
- ✓ This product should not be used for war weapons.
- ✓ All specifications are subject to change without notice.
- ✓ Be careful as strong magnetic fields may cause malfunction of the product.

