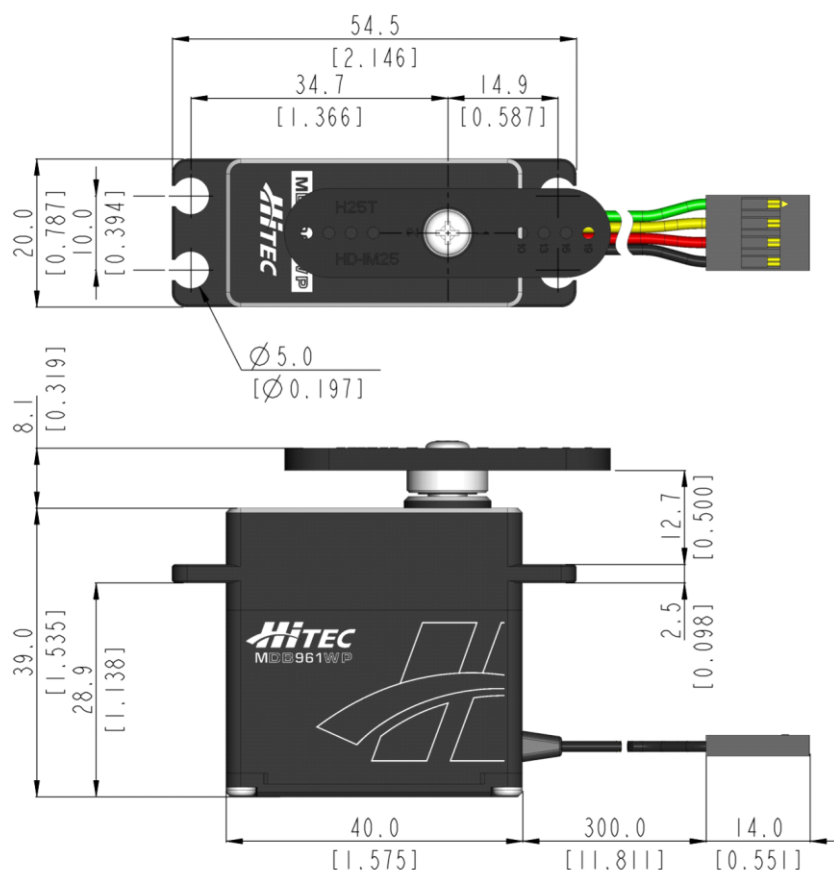


MDB961WP-CAN General Specification.



Control System	CAN 2.0A,B			-
Position Sensor Type	Contactless Magnetic Encoder			-
Motor Type	BLDC			At the Max voltage, it is recommended to be used only for a short time duration.
Operating Voltage Range	4.0 ~ 8.4V			
Voltage	-	6.0V	7.4V	At 25°C(±10%), 45%RH(±10%) <u>measurement environment</u>
No Load Speed	-	0.18sec/60°	0.15sec/60°	
Stall Torque	-	55.0kgf-cm (763.81oz-in)	55.0kgf-cm (763.81oz-in)	
Peak Efficiency Torque	-	11.0kgf-cm (152.76oz-in)	11.0kgf-cm (152.76oz-in)	
Standing Current	-	30mA	30mA	
No Load Running Current	-	500mA	500mA	
Stall Current	-	8,000mA	6,500mA	
Deadband	-	n/a	n/a	
Operating Travel	Servo Mode : ±60°(Default), ±150°(Programmable) / Turn Mode : ±32760 Turns			F/W v1.5 or Higher version
Continuous Rotation	n/a			-
Operating Temperature Range	-20°C ~ +60°C (-4°F ~+140°F)			-
Storage Temperature Range	-30°C ~ +80°C (-22°F ~+176°F)			-
Connector Wire Length	300mm (11.811inch)			
Connector Wire Gauge	20AWG			
Dimensions	40.0mm x 20.0mm x 39.0mm (1.575inch x 0.787inch x 1.535inch)			General Tolerance ±0.1mm
Weight	90.0g (3.175oz)			Excluding the weight of Horn
Bearing Type	2 Ball Bearing			-
Case Material	Aluminum Alloy			-
Gear Material	5 Hardened Steel Gears			-
Gear Train Backlash	Max 0.5°			-
Horn Gear Spline	25T(Ø6)			-
IP-Rating	IP67			-
Servo Amplifier Type	32bit programmable Digital			-



1:1 scale (Unit : mm[inch])

- This product should not be used directly on the human body for medical purposes.
- All specifications are subject to change without notice.
- Be careful as strong magnetic fields may cause malfunction of the product.

